





SMART AND VERSATILE

### **Maximize your cleaning** productivity and coverage

With its strong brush pressure and a cleaning efficiency up to 3,000 m<sup>2</sup>/h, Scrubber 75 is an ideal choice for large-area, heavy-duty cleaning. Simultaneous scrubbing and sweeping is achievable with roller brushes, and makes Scrubber 75 a competent cleaner for industrial sites where trash and debris are common on the floor. Its 270° rotational scrub deck enables cleaning tight corners and ensures maximal cleaning coverage.

- •Simultaneous scrubbing and sweeping
- •270° rotational scrub deck
- •Up to 3,000 m<sup>2</sup>/h cleaning efficiency

ADVANCED SENSING AND LIGHTING

### **An ultimate solution** for car park cleaning

Scrubber 75 P is customized for car park cleaning. It adopts automotive-level sensor and lighting configurations to work smartly and safely in the dynamic environment of parking lots where a large volume of vehicles going in and out. The robot also has an oil cleaning mode to deal with the stubborn oil stains that are common on the floors of the parking lots.

- Oil stain cleaning
- Millimeter-wave radars
- Advanced lighting configuration

**CLEANING MADE EFFORTLESS** 

### **Simplify your work process**

Scrubber 75 will make cleaning work much easier with little need for human interference. It perceives environmental changes, updates the map and reroutes itself in real time - you don't need to stand by to save it from getting lost or stuck. With the optional workstation, the robot can perform power charging and water refill by itself. It also offers remote access via Gausium mobile app that enables you to monitor and control your cleaning task from anywhere.

- Smart obstacle avoidance and rerouting
- •Remote-control mobile app
- One-stop service workstation

### **Key Features:**

### > Superb Productivity

- Integrating scrubbing, sweeping, dust mopping and degreasing
- Up to 3,000 m<sup>2</sup>/h cleaning efficiency

## ু Oil Stain Cleaning

Able to mark oil stains in the map and perform thorough oil cleaning

#### 270° Rotational Scrub Deck

Accessing and cleaning 90° corners, putting a stop to incomplete cleaning once and for all



Reducing around 80% freshwater consumption

# Ergonomic Manual Mode

Equipped with stand-on pedal and steering wheel for users to effortlessly carry the machine around

# Minimal Human Intervention

Optional workstation for self-docking charging, water refill and discharge

# - Advanced lighting system (75 P)

Adopting flashing light, blue projection light and supplement light, distinctively communicating the machine position through vehicle-identifiable signals



Market-leading sensor system consisting of 3D LiDAR, 2D Laser and 3D Cameras. 75 P is equipped with Millimeterwave radars for faster and more accurate perception of the vehicle movements

### **Superb performance in** a broad range of applications:

Shopping centers | Supermarkets | Parking lots | Transportation Hubs Manufacturing plants | Logistics warehouse | Plazas | etc.









Natural Stone

Artificial Marble / Ceramic Granite

**PVC & Vinvl** 



**GAUSIUM** 



Concrete

## **SPECIFICATION**

#### **DIMENSION**

DIMENSION		
Length	1,370 mm   54 in	
Width	962 mm   38 in	
Height	1,417 mm   56 in	
Unladen Weight	400 kg   900 lb	
Cleaning Width	750 mm   29 in	
CLEANING		
Max. Scrubbing Productivity	3,000 m <sup>2</sup> /h   32,300 ft <sup>2</sup> /h	
Brush Pressure	45 kg   99 lb	
Clean Water Tank	75 L   20 gal	
Recovered Water Tank	50 L   13 gal	
MOVEMENT		
Gradeability (Autonomous Cleaning)	5°	
Gradeability (Autonomous Driving)	8°	
Max. Moving Speed	1.1 m/s   2.5 mph	
Min. Passable Obstacle Height	10 mm   0.4 in	
Min. Turn-around Width (Autonomous)	2,000 mm   47 in	

### **ELECTRICAL**

Battery Type	Lithium Iron Phosphate
Battery Capacity	240 Ah
Rated Voltage	24 VDC
Max. Output Power	2,000 W   2.6 hp
Charging Time	5 hours
Uptime	≈ 4-6 hours
SENSING	
75 S	3D LiDAR, 2D LiDAR, 3D Depth Camera Air Pressure Collision Sensor
75 P	3D LiDAR, 2D LiDAR, 3D Depth Camera Air Pressure Collision Sensor, Millimeter-wave Radars



